			(3 hours			Total Mark	s: 80
NB	1) 2) 3)	Question No. 1 is comp Attempt any three que Figures to the right in	estions out o		aining five q	uestions.	
	4)	Assume suitable data			t justify the	same.	
Q1.		Attempt any four					(20)
	A.	Explain the difference between programmable and flexible automation.					
	B.	Explain Automation migration strategy. List and explain types of joints used in Robots.					
	C. D.	Identify the compone				the component.	
			1807 E		who was		
	Е.	What is an end effect	or? Explain	the magn	etic gripper	with suitable example.	
Q2	A.	Design electro Pneumatic circuit for two cylinder operation with following sequence using 5/2 both side solenoid operated valve as DCV. A+B+Delay B- A-					
ST. CY	В.	With user selection of Explain concept of A Terminologies of AN	rtificial Neu			ration. in detail. List and define	(10)
Q3	A.	What is a significance with example.	e of Cascado	e method?	List rules f	or cascade method along	(10)
	B.	Differentiate between	PLC and R	Relays.			(05)
<i>y</i> .	C.	Write short note on in		- / /	of Robots.		(05)
Q4	A.	Compare Supervised, parameters.	Unsupervis	sed and re	inforcement	t learning with different	(10)
	В.	Design simple pneum sequence using 4/2 pi	lot operated Delay B+	l valve as A+ A- B	DCV using	cascade method	(10)
		With user option of si	ingle cycle -	– multi cy	cle. Also dr	aw displacement diagram	•
Q5	A.	Explain depth first se	arch algorit	hm with e	xample.		(08)
	B. C.	Write note on different Explain linear regress					(05) (05)
Q6	Α.	Explain hierarchical (Clustering w	vith as exa	ample.		(08)
	B.	Write detail note on M	(\		-	s operations.	(05)
	C.	For a given data set [2 K=2 clusters.	2,4,10,12,3,	20,30,11,2	25], find the	final cluster centres using	g (05)